

## Liquid handling and robotics made easy

The Cavro Magni Flex represents a comprehensive, modular liquid handling framework that is designed to easily integrate into almost any system, in a wide range of laboratory processes – from molecular immunoassay processing to molecular diagnostics – allowing instrument designers to concentrate on their applications.

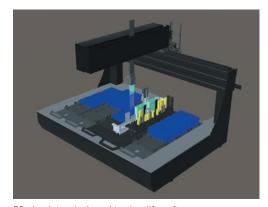


## **Key benefits**

- Versatile choose between liquid or air dispensing and various worktable sizes for your application requirement
- Adaptable and flexible two, four or eight\* independent Y and Z channels with variable spacing capabilities, enable the use of different labware formats to match the needs for your specific workflow
- Proven and reliable backed by Tecan's 40 years of development experience and commitment to highest standards
- **Channel grippers** use the existing channels as gripper extensions eliminates the need for an additional arm for labware handling
- Broad range of pipetting volumes the low maintenance Cavro Pulssar PBC Pumps offer a 5 to 1,000  $\mu$ l liquid handling range for broad application flexibility, and the new Air Restriction Pipetting Technology offers a volume range from 1  $\mu$ l to 5000  $\mu$ l
- Auto-alignment automatically align the robotic arm for quick on-site set-up
- Software development kit to accelerate end-user software development, offering:
  - Higher level command functions for easy robotic programming
  - Multichannel synchronization and collision avoidance
- Drag and drop customizable worktable editor
- **3D simulator** standalone software that emulates hardware commands in 3D, allowing methods to be developed, tested and improved before the hardware is even available

| Select   | Work flows                   | Status                         | Execution time  |
|----------|------------------------------|--------------------------------|---|
| <b>2</b> | BasicPoettingWorkflow        | Executing Workflow             |   |
| 131      | CustomLiquidClassWorkflow    | Not executed                   | 00,00000  |
| E3 :     | DemoModeWorkflow             | Not executed                   | 00,00000  |
|          | GripperToolhandlingWorkflow  | Not executed                   | 00:00:00  |
| 10       | LiquidLevelDetectionWorkflow | Not executed                   | 00:00:00  |
| 0        | MoveLabwareWorkflow          | Not executed                   | 00.00:00  |
| E3.      | MoveWorkflow                 | Not executed                   | 00:00:00  |
|          | RecoveryWorkflow             | Not executed                   | 00:00:00  |
|          |                              | Task                           |   |
|          |                              | Total Execution Time: 00/01:24 |   |
| utput    | Name -                       | The second second second       | Commercial |
| ot Exe   | Name -                       | The Control of the             |   |

Application-based examples to expedite workflow creation.



3D simulator designed to simplify software programming and testing.

The Cavro Magni Flex is the ideal starting platform for your next instrument design with multichannel liquid handling needs. Designed for OEM customers who are looking to quickly develop an automated liquid handling solution, the Cavro Magni Flex provides a core robotic architecture that can evolve into a complete automation solution addressing your specific application needs.

\*Not all configurations may be available in your region.

## **Specifications**

| Power requirements                            |  |  |  |  |  |
|---|--|--|--|--|--|
| Operating voltage                             | 100 to 240 VAC, 50/60 Hz   | 100 to 240 VAC, 50/60 Hz   |  |  |  |
| Power supply rating                           | 480 VA   | 480 VA   |  |  |  |
| Maximal power per output @ 24 V               | 95 W continuous, 200 W for m   | 95 W continuous, 200 W for max. 120 s  |  |  |  |
| Communications                                |  |  |  |  |  |
| To other Tecan Devices                        | CAN2 <sup>(0)</sup> 500 kb/s CAN1 <sup>(0)</sup> 10  | O kb/s USB RS232 RS485   |  |  |  |
| To host                                       | USB2   |  |  |  |  |
| Mechanical                                    |  |  |  |  |  |
| Travel length                                 | X-axis   | Y-axis   | Z-axis   |  |  |
|   |  | Functiona  | I / partial access   |  |  |
| 2-channel                                     | 3 Grid: 527mm  | 445 <sup>(1)</sup> / 454 <sup>(2)</sup> mm   |  |  |  |
| 4-channel                                     | 5 Grid: 803mm<br>9 Grid: 1355mm  | 388 <sup>(1)</sup> / 414 <sup>(2)</sup> mm   | 1.77   |  |  |
| 4 Charmer                                     |  | 300 / 414 11111  | ≥143 <sup>(3)</sup> / ≥180 <sup>(4)</sup> mm   |  |  |
| 8-channel                                     | 5 Grid: 764mm<br>9 Grid: 1316mm  | 353 <sup>(1)</sup> / 414 <sup>(2)</sup> mm   |  |  |  |
| Maximum speed                                 |  |  |  |  |  |
| Speed   | 750 mm/s   | 300 mm/s   | 400 mm/s   |  |  |
| Acceleration                                  | 1,000 mm/s <sup>(5,6)</sup><br>900 mm/s <sup>(7)</sup>                                       | 1,500 mm/s <sup>(2)</sup>  | 2,400 mm/s <sup>(2)</sup>  |  |  |
| Resolution                                    | 0.02 mm  | 0.05 mm  | 0.0013 mm  |  |  |
| Payload (per channel gripper pair)            | N/A  | N/A  | 400 g  |  |  |
| Accuracy                                      | ± 0.5 mm   | ± 0.5 mm   | ± 0.5 mm   |  |  |
| Dimensions                                    | 3 Grid Deck  | 5 Grid Deck  | 9 Grid Deck  |  |  |
| Width   | 878 mm   | 878 mm   | 878 mm   |  |  |
| Length  | 737.5 mm   | 737.5 mm   | 737.5 mm   |  |  |
| Height  | 795.5 mm   | 795.5 mm   | 795.5 mm   |  |  |
| Weight<br>Liquid dispensing<br>Air dispensing | 32.2 <sup>(5)</sup> kg<br>36.7 <sup>(5)</sup> / 37.5 <sup>(6)</sup> / 42.7 <sup>(7)</sup> kg | 39.2 <sup>(5)</sup> / 41.7 <sup>(6)</sup> / 49.9 <sup>(7)</sup> kg<br>43.6 <sup>(5)</sup> / 44.4 <sup>(6)</sup> / 49.6 <sup>(7)</sup> kg | 53 <sup>(5)</sup> / 55.6 <sup>(6)</sup> / 63.7 <sup>(7)</sup> kg<br>57.4 <sup>(5)</sup> / 58.2 <sup>(6)</sup> / 63.4 <sup>(7)</sup> kg |  |  |
| Pipetting                                     | Pipetting Precision (Precision CV)   | Volume Range   | Process Security   |  |  |
| Liquid System                                 | 5 μl: ≤ 10%<br>50 μl≤ 2%<br>1000 μl: ≤ 1%  | 5 μl to 1000 μl  | cLLD (capacitive Liquid Leve   |  |  |
| Air System                                    | 1 μl: ≤ 5%<br>200 μl: ≤ 2%<br>1000 μl: ≤ 2%  | 1μl to 5000 μl   | detection)   |  |  |
|   | X-axis   | Y-axis   | Z-axis   |  |  |
| Motor driver technology                       | Field-oriented control with incre<br>mental encoder  | DC with incremental encoder  | DC with incremental encoder  |  |  |
| Options                                       |  |  |  |  |  |
| Tecan tip option                              | Standard fixed tips <sup>(8)</sup><br>Disposable tips <sup>(9)</sup>                         |  |  |  |  |
| Software and programming                      |  |  |  |  |  |
| Required OS                                   | Windows® 10 OS   |  |  |  |  |
| Software                                      | MAPlinx Setup Software<br>MAPlinx Development Kit<br>(C# Development Infrastructure          |  |  |  |  |
| Environment requirements                      |  |  |  |  |  |
| Operating                                     | 15-32 °C / 59-90 °F  |  |  |  |  |
|   | 30-60 % relative humidity, not   | 30-60 % relative humidity, not condensing at 30 °C / 86 °F   |  |  |  |
|   | Altitude 0-2,000 m above sea   |  |  |  |  |
| 1) Each channel individually (4               | 3) With standard fixed tips (64) With Disposable tips (7                                     | (s) With 4 Channel Arm (s) With 8 Channel Arm (s) With Liquid dispensing only  | (9) With Air Dispensing only (ARP)   |  |  |

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